

3D Mapping and Traversal

Autonomous navigation and obstacle avoidance using State of the Art Intel Depth Sensing Cameras

• Supports SLAM variable navigation

• Payload accessible data streams

Asset Management

Advanced power and data management to meet the demands of multiple payloads throughout mission critical phases and rover idle.

- Collect and analyse payload and vehicle health data
- Priority tasking of available resources
- On-demand provisioning

Payload-Driven

Manifest plug-and-play payloads for internal or external missions, from software defined control to drilling or long range testing.

- Co-manifested payloads with tasking available
- Payload defined mission profiles

Payload	System Specifications	
	Power	350Wh/day @ 5/12V
	Data	CAT6 Ethernet (250 MHz)
	Lifetime	2 weeks min., up to 2 yrs
	Payload Capacity	20 kg
	Payload Size	300 × 300 × 500 mm
	Software	Robot Operating System 2
Rover	Traversal	20° incline, 7.5 cm obstacle
	Enivironment	-50°C to 32°C
	Thermal Control	Available upon Request



Test-as-a-Service

Rugged design for the most extreme terrestrial climates

- The Scout is ready-to-deploy with its own control systems, just integrate your chosen payload
- Thermal and Radiation management available
- •On-site and remote mission control and support
- Integration, deployment, and retrieval offered